### Rad-hard Location and Attitude Module (R-LAM), Phase I



Completed Technology Project (2010 - 2010)

#### **Project Introduction**

R-LAM (Rad-hard Location and Attitude Module), promises a new generation of both integrated navigation modules and stand-alone navigation subsystems including nav-grade IMU's, atomic-precision clocks and GPS units compliant with the Space Plug and Play Architecture (SPA) initiative. R-LAM leverages two active DARPA MTO programs. In the Navigation-Grade Integrated Micro-Gyroscope (NG-IMG) project, Archangel Systems, Inc. has developed a MEMS IMU called NG-MARS - a spinning mass IMU with navigation-grade performance. In DARPA's Chip-Scale Atomic Clock (CSAC) program, Symmetricom, Inc has developed a clock that is 50-100X smaller and lower power than any previous atomic clock technology, while exhibiting short-term stability of  $\Box y(\tau) < 1x10-10/\Box 1/2$  and long-term drift of  $< 3 \times 10-10/month$ . NASA-Goddard has constructed a rad-hard GPS called Navigator for the Magnetospheric Multiscale (MMS) program. Designed for high elliptical orbits (HEO), Navigator uses NASA's Geon algorithms. Currently Navigator weight and power exceeds R-LAM requirements. NASA-Goddard colleagues will advise the R-LAM team as they transition Navigator hardware. Intrinsix Corp. is an ASIC design house skilled in rad-hard mixed-signal design. They will implement rad-hard support electronics for NG-MARS, CSAC and Navigator. Intrinsix is familiar with NASA's SPA initiatives and will design the R-LAM interface for compliance.

#### **Primary U.S. Work Locations and Key Partners**





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#### Small Business Innovation Research/Small Business Tech Transfer

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| Organizations<br>Performing Work | Role                       | Туре           | Location                     |
|----------------------------------|----------------------------|----------------|------------------------------|
| Archangel Systems                | Lead<br>Organization       | Industry       | Auburn,<br>Alabama           |
| Ames Research Center(ARC)        | Supporting<br>Organization | NASA<br>Center | Moffett Field,<br>California |

| Primary U.S. Work Locations |            |
|-----------------------------|------------|
| Alabama                     | California |

#### **Project Transitions**

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January 2010: Project Start



July 2010: Closed out

#### **Closeout Documentation:**

• Final Summary Chart(https://techport.nasa.gov/file/139361)

# Organizational Responsibility

# Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

#### **Lead Organization:**

Archangel Systems

#### **Responsible Program:**

Small Business Innovation Research/Small Business Tech Transfer

# **Project Management**

#### **Program Director:**

Jason L Kessler

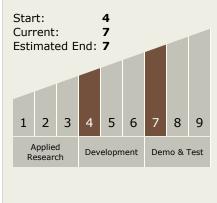
#### **Program Manager:**

Carlos Torrez

#### **Principal Investigator:**

William C Dillard

# Technology Maturity (TRL)





Small Business Innovation Research/Small Business Tech Transfer

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# **Technology Areas**

#### **Primary:**

- TX05 Communications, Navigation, and Orbital Debris Tracking and Characterization Systems
  - └─ TX05.4 Network Provided Position, Navigation, and Timing
    - ─ TX05.4.1 Timekeeping and Time Distribution

## **Target Destinations**

The Sun, Earth, The Moon, Mars, Others Inside the Solar System, Outside the Solar System

